

MOTION CONTROLLERS **SOLOIST LINEAR**



Left: Soloist HLe; Above: Soloist ML

Aerotech's Soloist® linear series are single-axis servo controllers that combine a power supply, amplifier, and position controller in a single package. The Soloist can control up to five tasks simultaneously, as well as handle variables and manage I/O, making it well-suited for demanding production applications. The Soloist has high-speed position latch inputs and advanced data logging capabilities, making it ideal for laboratory and test instrument applications. The advanced software architecture shortens customer development time, while including support for C#, VB.Net, C, and LabVIEW®, combined with our full IDE and multitasking operating system. Host-mode operation allows you to send commands with your PC via Ethernet or USB for immediate execution.

The Soloist HLe/ML, with linear power stage, is available for low noise and ultra-high-performance applications. This controller is ideal for high bandwidth requirements and maintains superb linearity and zero crossover distortion. For example, applications that have many motion reversals and that require high position accuracy will benefit from using the Soloist linear series.

The Soloist ML provides a very small package linear power stage

for high position-accuracy applications.

Motion Composer, the common integrated development environment for all Aerotech controllers, provides users with Windows®-based software with powerful diagnostic, debug, and analysis tools for OEMs and end users alike.

Allen-Bradley Interface

Combine proven PLC with proven motion control for easier integration, startup, and maintenance of medium- and high-end automation projects. The Aerotech EtherNet/IPTM interface enables AB PLCs (MicroLogix, CompactLogix™, or ControlLogix) to be integrated directly with the Soloist. Motion can be directly programmed in the RSLogix 5000 environment or separate programs can be written on the controller and triggered from the AB PLC. Aerotech has two interfaces: ASCII and Register. Choose the PLC, motion controller, and interface that best fits your application needs.

Total Solution

The controllers are fully tested and ready to run right out of the box. Aerotech can integrate the Soloist into a complete motion

— PRODUCT HIGHLIGHTS —

Single axis digital servo controller with integral power supply and amplifier

Advanced software architecture shortens customer development time; use .Net, C#, C, and LabVIEW® combined with our full IDE and multitasking operating system

Ideal for simple applications with minimal setup or complex applications that use the full flexibility and scalability

Linear amplifier (HLe/ML) for low noise, ultra-high-performance applications

CE approved and NRTL safety certification; follows the 2011/65/EU RoHS 2 Directive

Allen-Bradley EtherNet/IPTM interface provides full integration with the Soloist; program the Soloist directly from RSLogix™ 5000

Output power range is 10 to 20 A peak with ±10 to ±80 VDC bus

system, removing the burden of parameter setup and axis tuning.

Practical Power

Each series is capable of driving a wide range of motors including brushless, DC servo, and microsteppers. Brushless motors are sinusoidally commutated to minimize torque ripple.

Using a digital servo loop with feedforward, the Soloist tightly tracks velocity and position trajectories with virtually zero error. On-board autotuning and built-in calculators make servo tuning simple.

Variables, Math and More

With variables and math capability, one program can be used to produce a variety of parts by simply prompting the user for new application data.

Application Versatility

The Soloist has other built-in features such as axis calibration and backlash compensation, so you can maximize your machine's accuracy and precision. The "user units" feature makes it easy to customize the Soloist to your specific machine, allowing custom units for both linear and rotary applications.

The controller is equipped with dual encoder inputs, so you can tackle master-slave applications or achieve higher accuracies with dual-loop control. Precise registration-based moves are also possible because of the fast 0.1 microsecond acknowledge time of the Soloist. The Soloist easily handles complex functions such as output-on-the-fly and velocity profiling.

Soloist Comparison Chart	Soloist HLe	Soloist ML
PC Interface	Ethernet TCP/IP or USB	Ethernet TCP/IP or USB
Current Output, Peak ¹	10-20 A ²	10 A ²
Current Output, Continuous ¹	5-10 A ²	5 A ²
Bus Voltage	±40-80 VDC ³	±40 VDC ³
Amplifier Type	Linear	Linear
Motor Supply Voltage	2 Phase AC	DC
Standard I/O ⁴	4-DO/6-DI 1-AO/1-AI	1-AI
Expansion I/O ⁴ (Additional to Base I/O)	16-DO/16-DI 3-AO/3-AI	8-DO/8-DI 1-AO/1-AI
Single Axis PSO ⁵	Yes	Yes
Dual Axis PSO ⁵	Yes	No
Triple Axis PSO ⁵	Yes	No
Ethernet Capable for Third Party I/O	Optional	No

¹ Peak value of the sine wave; rms current for AC motors is 0.707 * Apk.

² Load dependent.

³ Output voltage is load dependent.

⁴ DO = Digital Output; DI = Digital Input; AO = Analog Output; AI = Analog Input.

⁵ PSO not available on Soloist ML when using integral MXU.

Soloist HLe Specifications

Specifications	Units	10-40	20-40	10-60	10-80
Motor Style		Brush, brushless, voice coil, stepper			
Motor Supply	VAC	115/230; 50/60 Hz; factory configured			
Control Supply ¹	VAC	85-240 VAC; 50/60 Hz			
Bus Voltage ²	VDC	±40	±40	±60	±80
Peak Output Current (1 sec) ^{3,4}	A _{pk}	10	20	10	10
Continuous Output Current ^{3,4}	A _{pk}	5	10	5	5
Digital Inputs		6 Optically Isolated (2 High Speed)			
Digital Outputs		4 Optically Isolated			
Analog Inputs		One 16-bit Differential; ±10 V			
Analog Outputs		One 16-bit Single-Ended			
Dedicated Axis I/O on Feedback Connector		Three Limit Inputs (CW, CCW, Home); Three Hall Effect Inputs (A, B, C); Three High-Speed differential Inputs (sin, cos, mkr for encoder); Motor Over-Temperature Input			
Dedicated I/O on Auxiliary Feedback Connector		sin, cos, mkr for Aux Enc; Aux Enc can be used for PSO Output			
I/O Expansion Board ⁵		16/16 Digital Opto-Isolated; 3 Analog In (±10 V, 16-bit Differential); 3 Analog Out (±10 V, 16-bit)			
High Speed Data Capture		Yes (50 ns Latency)			
Automatic Brake Control		Standard; 24 V at 1 A			
Emergency Stop Sense Input (ESTOP) ⁶		Standard; 24 V Opto-Isolated			
Position Synchronized Output (PSO)		Single Axis Standard, Two/Three Axis Optional			
Can Output Multiplied Encoder		Yes			
Can Output Square Wave Encoder		Yes			
Primary Encoder Input Frequency		32 MHz Square Wave Standard; 500 kHz Sine Wave (MXH)			
Secondary Encoder Input Frequency		32 MHz Square Wave			
Encoder Multiplication		Up to x65536 with Quadrature Output (MXH)			
Absolute Encoder		Renishaw Resolute BiSS; EnDat 2.1; EnDat 2.2			
Resolver Interface		Optional; 1 or 2 Channel; 16-bit			
Internal Shunt Resistor		N/A			
External Shunt		N/A			
Ethernet		Optional			
USB		No			
RS-232		Yes			
FireWire		No			
Fieldbus		Modbus TCP; Ethernet/IP			
Current Loop Status Update Rate	kHz	20			
Servo Loop Update Rate	kHz	10			
Power Amplifier Bandwidth	kHz	Selectable through software			
Minimum Load Inductance	mH	0			
Operating Temperature	°C	0 to 50			
Storage Temperature	°C	-30 to 85			
Weight	kg (lb.)	10.36 (22.8)			
Standards		CE approved, NRTL safety certification, 2011/65/EU RoHS 2 Directive			

¹ "Keep Alive" supply.

² Output voltage dependent upon input voltage.

³ Peak value of the sine wave; rms current for AC motors is $0.707 * A_{pk}$.

⁴ Load dependent.

⁵ Requires I/O option.

⁶ Requires external relay to remove motor supply power.

Soloist ML **Specifications**

Specifications	Units	
Motor Style		Brush, brushless, voice coil, stepper
Motor Supply	VAC	±40 max
Control Supply ¹	VAC	18-36 VDC
Bus Voltage ²	VDC	±40
Peak Output Current (1 sec) ^{3,4}	A _{pk}	10
Continuous Output Current ^{3,4}	A _{pk}	5
Digital Inputs		N/A
Digital Outputs		N/A
Analog Inputs		One 16-bit Differential; ±10 V
Analog Outputs		N/A
Dedicated Axis I/O on Feedback Connector		Three Limit Inputs (CW, CCW, Home); Three Hall Effect Inputs (A, B, C); Three High-Speed differential Inputs (sin, cos, mkr for encoder); Motor Over-Temperature Input
Dedicated I/O on Auxiliary Feedback Connector		sin, cos, mkr for Aux Enc; Aux Enc can be used for PSO Output
I/O Expansion Board ⁵		8/8 Digital Opto-Isolated; 1 Analog In (±10 V, 16-bit Differential); 1 Analog Out (±5 V, 16-bit)
High Speed Data Capture		Yes (50 ns Latency)
Automatic Brake Control		Optional
Emergency Stop Sense Input (ESTOP) ⁶		Standard; 24 V Opto-Isolated
Position Synchronized Output (PSO)		Single Axis Only
Can Output Multiplied Encoder		Yes (MXH Only)
Can Output Square Wave Encoder		Yes
Primary Encoder Input Frequency		32 MHz Square Wave Standard; 2 MHz Sine Wave (MXU or MXH)
Secondary Encoder Input Frequency		32 MHz Square Wave
Encoder Multiplication		Up to x4096 (MXU); Up to x65536 with Quadrature Output (MXH)
Resolver Interface		N/A
Internal Shunt Resistor		N/A
External Shunt		N/A
Ethernet		Yes
USB		No
RS-232		Yes
FireWire		No
Fieldbus		Modbus TCP; Ethernet/IP
Current Loop Status Update Rate	kHz	20
Servo Loop Update Rate	kHz	10
Power Amplifier Bandwidth	kHz	Selectable through software
Minimum Load Inductance	mH	0
Operating Temperature	°C	0 to 50
Storage Temperature	°C	-30 to 85
Weight	kg (lb.)	0.45 (1.0)
Standards		CE approved, NRTL safety certification, 2011/65/EU RoHS 2 Directive

1 "Keep Alive" supply.

2 Output voltage dependent upon input voltage.

3 Peak value of the sine wave; rms current for AC motors is $0.707 * A_{pk}$.

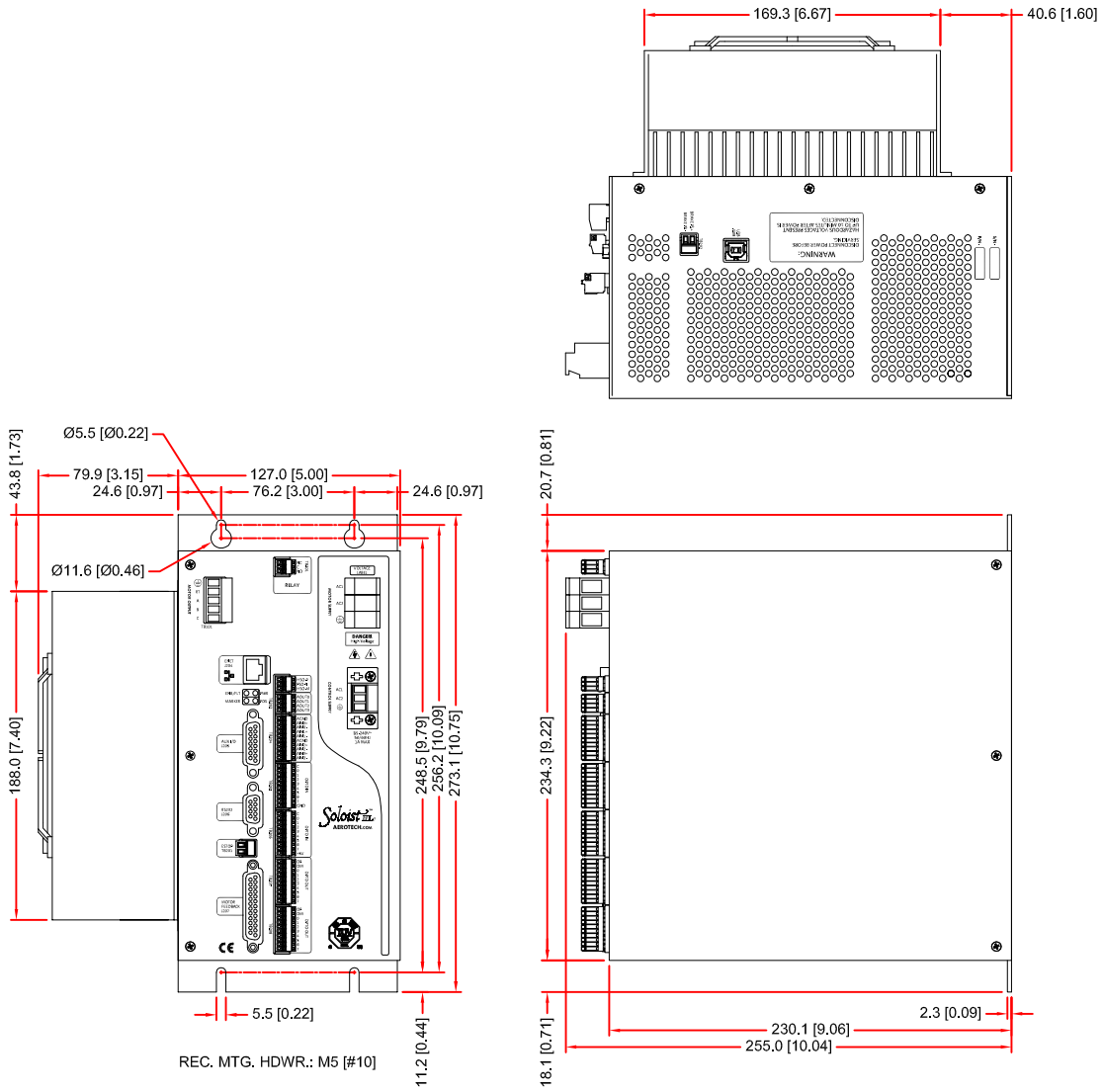
4 Load dependent.

5 Requires I/O option.

6 Requires external relay to remove motor supply power.

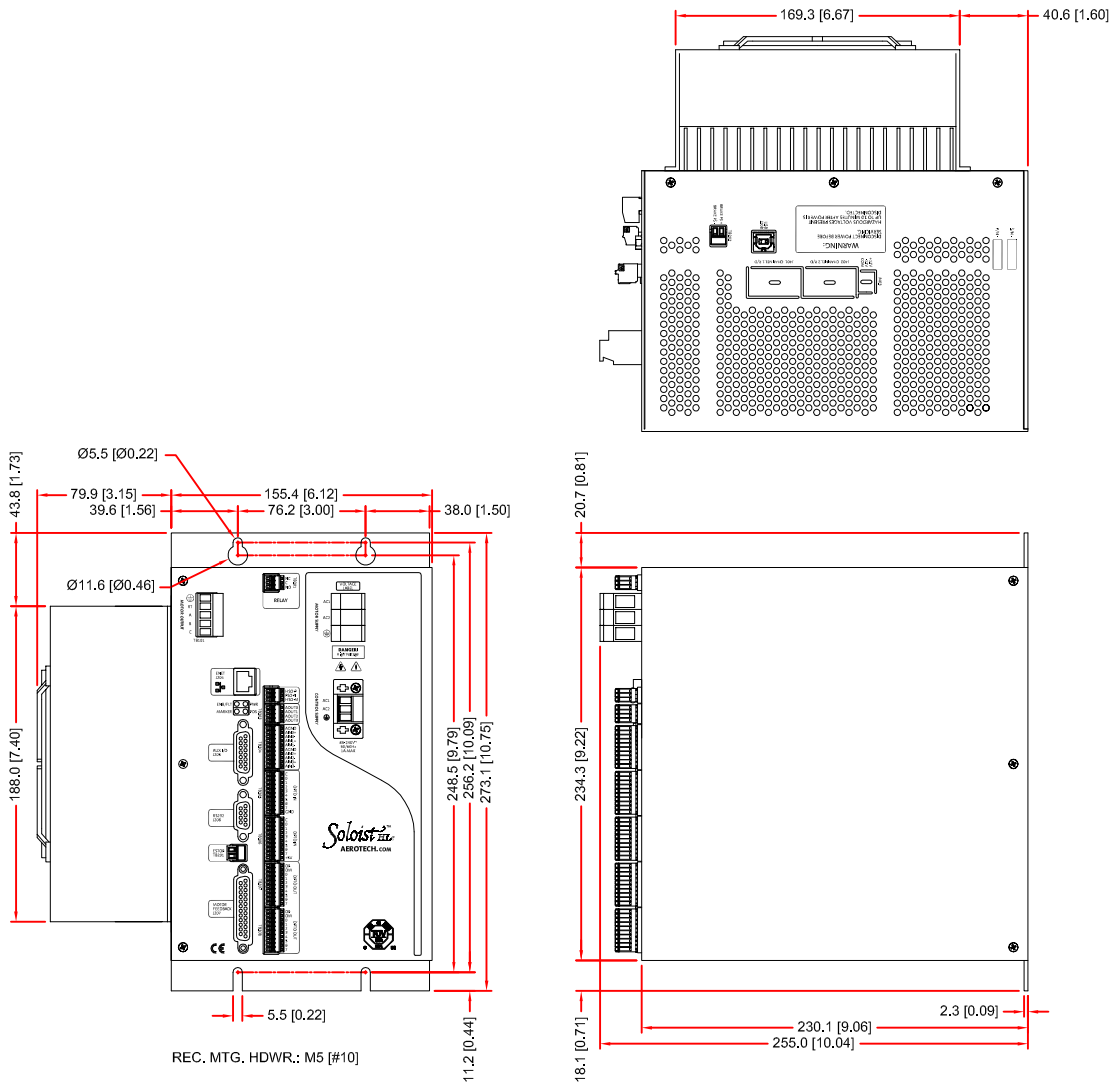
Soloist Linear Dimensions

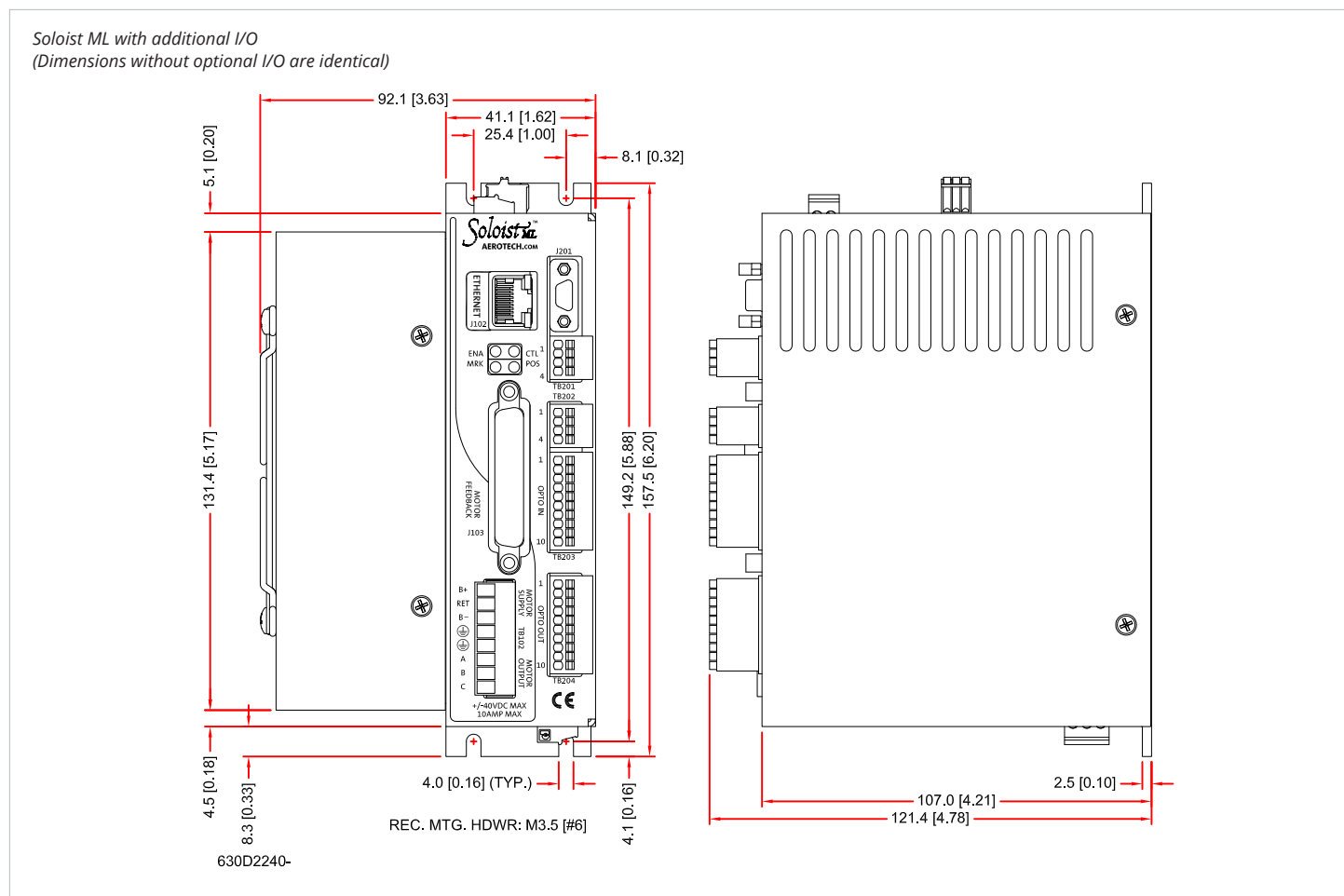
Soloist HLe



Soloist Linear Dimensions

Soloist HLe with Additional i/O



Soloist Linear **Dimensions**Soloist Linear **Ordering Information**

Visit Aerotech's website for complete ordering information.